

PCA<sub>1</sub>

# Upgraded Model

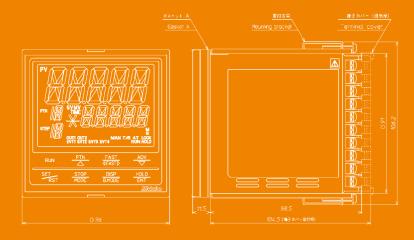
# **Enhanced Performance and Functions**







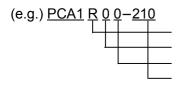
16-patterns 16-steps, A maximum of 256 programmable steps *Easy status checking using 3-color switching* 



USB Cable powered, Quick Setup using a USB Communication Cable

Drip-proof / Dust-proof IP66 (front panel only)

#### ■ Model



Control output: Relay contact Power supply: 100 to 240 V AC

Input: Multi-range

Option 1: Serial communication RS-485

Option 2: Transmission output (4 to 20 mA DC)

Option 3: Option 3 not needed

PCA1	Control Output	Power Supply	Input (*1)	Option 1 (*2)	Option 2 (*2)	Option 3 (*2)	Specification	
CA1		11 7	( )	( /	. ,	( /		
	R						Relay contact: 1a1b	
	S						Non-contact voltage (for SSR drive): 12 V DC±15%	
	Α						Direct current: 4 to 20 mA DC	
'.		0					100 to 240 V AC (Standard)	
		1					24 V AC/DC	
			0 — Multi-range (*1)					
				0			Option 1 not needed	
				1			Serial communication RS-232C	С
				2			Serial communication RS-485	C5
				3			Time signal output	TS
				4			Serial communication RS-232C+Time signal output	C+TS
				5			Serial communication RS-485+Time signal output	C5+TS
					0		Option 2 not needed	
					1		Transmission output (4 to 20 mA DC)	TA
					2		Transmission output (0 to 1 V DC)	TV
						0	Option 3 not needed	
						1	Heating/Cooling control output OUT2 Relay contact output (*3)	DR
						2	Heating/Cooling control output OUT2 Non-contact voltage output (*3)	DS
						3	Heating/Cooling control output OUT2 Direct current output (*3)	DA

- (\*1) Thermocouple, RTD, Direct current or DC voltage can be selected by keypad.
- (\*2) Only one option can be selected from Option 1, Option 2 and Option 3 respectively.
- (\*3) If Heating/Cooling control (DR, DS or DA option) is ordered, Event output EV2 is not available.

## ■ Accessories Sold Separately

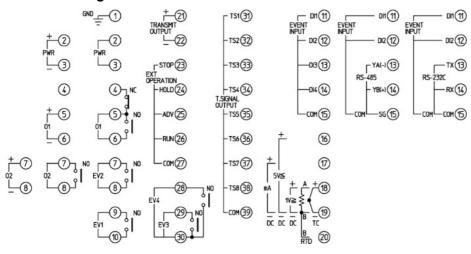
Model				
Terminal cover (TC-FCD)				
USB communication cable (CMB-001)				

# ■ Specifications

Input	Thermocouple: K, J, R, S, B, E, T, N, PL-II, C (W/Re5-26) External resistance: 100 Ω max.(However, B: 40 Ω max.)
	RTD: Pt100, JPt100, 3-wire type, Allowable input lead wire resistance: 10 Ω max. per wire (However, Pt100,
	-100.0 to 100.0°C: 5 Ω max.)
	Direct current: 0 to 20 mA, 4 to 20 mA DC
	Input impedance: 50 Ω, Allowable input current: 100 mA max.
	Direct voltage: 0 to 10 mV DC, -10 to 10 mV DC, 0 to 50 mV DC, 0 to 100 mV DC, 0 to 1 V DC
	Input impedance: 1 M $\Omega$ min., Allowable input voltage: 5 V DC max.
	Allowable signal source resistance: 2 k $\Omega$ max. (0 to 1 V DC), 200 $\Omega$ max. (0 to 100 mV DC, 0 to 50
	mV DC), 40 Ω max.(-10 to 10 mV DC), 20 Ω max.(0 to 10 mV DC)
	0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	Input impedance: 100 k $\Omega$ min. Allowable input voltage: 15 V DC max. Allowable signal source
	resistance: 100 Ω max.

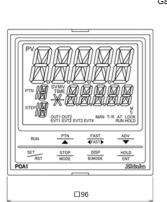
Basic accuracy	Thermocouple: Within ±0.2% of								
		ıt, 0 to 200℃ (32 to 392	- ,						
	B input, 0 to 300℃ (0 to 572℉): Accuracy is not guaranteed.								
	K, J, E, T, N input,	Less than 0°C (32°F): W	ithin ±0.4% of input span ±1	digit					
	RTD: Within ±0.1% of each inp	ut span±1 digit							
	Direct current: Within ±0.2% of	each input span±1 digit	:						
	DC voltage: Within ±0.2% of ea								
Input sampling period	125 ms	, ,							
Control output		apacity: 3 A 250 V AC (r	esistive load) 1 A 250 V AC	(inductive load $\cos \phi = 0.4$ )					
Common Campan	Relay contact 1a1b: Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load $\cos \phi = 0.4$ )  Electrical life: 100,000 cycles								
	Non-contact voltage (for SSR drive): 12 V DC±15%								
	Max. 40 mA (short circuit protected)								
	Direct current: 4 to 20 mA DC (Resolution: 12000)								
		d resistance: Max. 600	•						
Event output EV1	Relay contact 1a								
Event output EV i	Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load $\cos \phi = 0.4$ )								
	Electrical life: 100,000 cycles	(10313tive 10dd), 17423	o v Ao (maactive load cos ¢	7-0.4)					
Event output EV2									
Eveni output Evz	Relay contact 1a								
	Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load cos φ = 0.4)								
F. (2 mt 2 ) track F\/2 F\/4	Electrical life: 100,000 cycles								
Event output EV3, EV4	Relay contact 1a								
	Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load $\cos \phi = 0.4$ )								
	Electrical life: 100,000 cycles Event output EV3 and EV4 share one common terminal.								
			al.						
Program performance	Number of patterns: 16 (Linkable)								
	Number of steps: 256 (16 steps/pattern)								
	Number of repetitions: 0 to 9999 times (Repetitions disabled when set to 0.)								
	Program time range: 0 to 99 hours 59 minutes/step, or 0 to 99 minutes 59 seconds/step								
	(When  - - -  is set: Fixed value control is performed using step SV.)								
	Wait value: Thermocouple, RTD input without decimal point: ±(0 to 100)℃ (℉)								
	Thermocouple, RTD input with decimal point: ±(0.0 to 100.0)°C (°F)								
	DC voltage, current input: ±(0 to 1000)(The placement of the decimal point follows the								
	selection.)								
	(The Wa	ait function is disabled w	hen set to 0 or 0.0.)						
Serial communication	Communication line: EIA	RS-232C (C option), ElA	A RS-485 (C5 option)						
(optional)	Communication method: Half-duplex communication								
	Synchronization method: Start-stop synchronization								
	Communication speed: 9600, 19200, 38400 bps (Factory default: 9600 bps)								
	Data bit: 7 or 8 (Factory default: 7 bits)								
	Parity: Even, Odd, No parity	Parity: Even, Odd, No parity (Selectable by keypad) (Factory default: Even)							
	Stop bit: 1 or 2 (Selectable by	keypad) (Factory defaul	t: 1)						
	Data format:								
	Communication protocol	Shinko protocol	Modbus ASCII	Modbus RTU					
	Start bit	1	1	1					
	Data bit	7	7 or 8	8					
	Parity	Even	Even (No parity, Odd)	No parity (Even, Odd)					
	0, 1,11		Selectable	Selectable					
	Stop bit	1	1 or 2	1 or 2					
	SV digital transmission: If 'SV digital transmission' is selected in [Communication protocol] in Serial								
	communication, SV can be digitally transmitted to Shinko indicating controllers (with Seria								
	communication C5 option).								
	Update	Update cycle: 250 ms							
Time signal output	Number of circuits: 8								
(optional)	Open collector: Capacity: 24 V	DC, Max. 50 mA							
Transmission output	Resolution: 12000								
(optional)	Output: TA option: 4 to 20 mA DC (Load resistance: Max. 500 Ω)								
,	TV option: 0 to 1 V DC (Load resistance: Min. 100 kΩ)								
	Output accuracy: Within ±0.3% of Transmission output span								
Heating/Cooling control	If the D□ option is ordered, Ev	•	•						
output (optional)	•	•		250 V AC (inductive load					
output (optional)	Relay contact 1a (DR option): Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load								
	cos φ = 0.4)  Flectrical life: 100 000 cycles								
	Electrical life: 100,000 cycles Non-contact voltage(for SSR drive) (DS option): 12 V DC±15%								
	Max. 40 mA (short circuit protected)								
	Direct current (DA option): 4 to 20 mA DC (Resolution: 12000)								
	Loa	d resistance: Max. 600	.2						

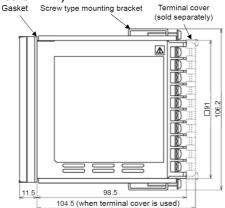
### **■Terminal Arrangement**

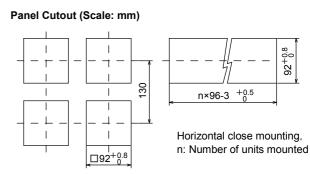


GND	Grounding
PWR	Power supply 100 to 240 V AC or 24 V AC/DC
	For a 24 V AC/DC power source, ensure polarity is correct when using direct current (DC).
01	Control output OUT1
02	Control output OUT2 (DR, DS or DA option)
EV1	Event output EV1
EV2	Event output EV2
EV3	Event output EV3
EV4	Event output EV4
EVENT INPUT	Event input
RS-485/RS-232C	Serial communication RS-485 (C5 option) or RS-232C (C option)
TC	Thermocouple input
RTD	RTD input
DC 1V≧	DC voltage input: 0 to 10 mV DC, -10 to 10 mV DC, 0 to 50 mV DC, 0 to 100 mV DC, 0 to 1 V DC
DC 5V≦	DC voltage input: 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
DC mA	Direct current input: 0 to 20 mA DC, 4 to 20 mA DC
TRANSMIT OUTPUT	Transmission output (TA or TV option)
EXT OPERATION	External operation input: STOP, HOLD, ADV, RUN
T.SIGNAL OUTPUT	Time signal output (TS option)

#### **■ External Dimensions** (Scale: mm)









- To ensure safe and correct use, thoroughly read and understand the manual before using this instrument.
  This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after consulting purpose of use with our agency or main office.
  (Never use this instrument for medical purposes with which human lives are involved.)

  External protection devices such as protection equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Also proper periodic maintenance is required.
- This instrument must be used under the conditions and environment described in the manual. Shinko Technos Co.,
   Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

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- Photos used in this catalog do not show unit in operating status.
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